

Generic Lambdas

Chapter 2 Conditionally Safe Features

Not only is the argument v constrained to being a vector, but the deduced element type T is available for use within the function. The same sort of pattern matching is not available portably for generic lambdas:

```
auto y1 = [](std::vector<auto>& v) { }; // Error, auto as template parameter
```

Constraining the deduced type of an **auto** parameter using metaprogramming, e.g., through the use of std::enable_if, is sometimes possible:

The y2 closure can be called only with a vector. Any other type will fail substitution because is_same will return false if substitution even gets that far; substitution might fail earlier if the type for v does not have a nested value_type. Passing nonvector arguments to this constrained lambda will now fail at the call site, rather than, presumably, failing during instantiation of y2(v):

For all of the additional complication in y2, the element type for our vector is still not available within the lambda body, as it was for the function body for f1, above; we would need to repeat the type name typename std::remove_reference_t<decltype(v)>::value_type if the element type became necessary.

This annoyance is of no practical significance because lambda expressions cannot be overloaded. In the absence of overloading, there is little benefit to removing a call from the overload set compared to simply letting the instantiation fail, especially as most lambda expressions are defined at the point of use, making it comparatively easy to diagnose a compilation problem if one occurs. Moreover, this point-of-use definition is already tuned to the expression of the code.

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